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(PATENT)

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Application of:
Andrew Bellchambers

Application No.: 10/706,201

Group Art Unit: Not Yet Assigned

Filed: November 12, 2003

Examiner: Not Yet Assigned

For: METHOD OF HANDLING A LOAD

TRANSMITTAL OF PRIORITY DOCUMENT

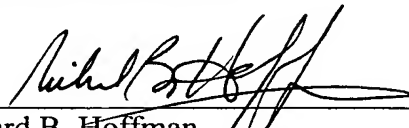
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Dear Sir:

Enclosed herewith is a certified copy of Great Britain Application No. 0226417.4, filed November 13, 2002, upon which priority of the instant application is claimed under 35 U.S.C. 119.

Dated: January 9, 2004

Respectfully submitted,

By 
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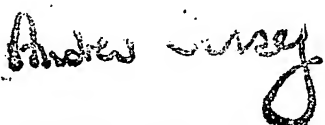
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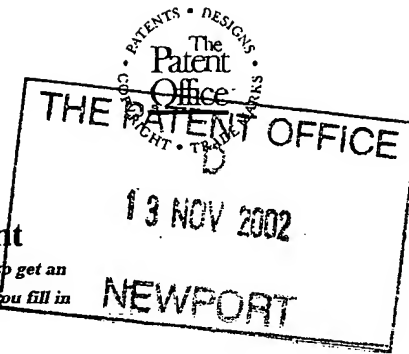
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Dated 12 November 2003

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13 NOV 02 07:30:40-1/0026417.4
P01/7700 0.00-0226417.4
1/77

Request for grant of a patent

(See the notes on the back of this form. You can also get an explanatory leaflet from the Patent Office to help you fill in this form)

The Patent Office

Cardiff Road
Newport
South Wales
NP10 8QQ

1. Your reference

A10634GB-DJL/jan

2. Patent application number

(The Patent Office will fill in this part)

0226417.4

13 NOV 2002

3. Full name, address and postcode of the or of each applicant (*underline all surnames*)

J.C.Bamford Excavators Limited
Rocester
Staffordshire
ST14 5JP

Patents ADP number (*if you know it*)

5520758001

If the applicant is a corporate body, give the country/state of its incorporation

United Kingdom

4. Title of the invention Method of Handling a Load

5. Name of your agent (*if you have one*)

Forrester Ketley & Co.

"Address for service" in the United Kingdom to which all correspondence should be sent (*including the postcode*)

Chamberlain House
Paradise Place
Birmingham
B3 3HP

Patents ADP number (*if you know it*)

133005

6. If you are declaring priority from one or more earlier patent applications, give the country and the date of filing of the or of each of these earlier applications and (*if you know it*) the or each application number

Country

Priority application number
(*if you know it*)

Date of filing
(*day / month / year*)

7. If this application is divided or otherwise derived from an earlier UK application, give the number and the filing date of the earlier application

Number of earlier application

Date of filing
(*day / month / year*)

8. Is a statement of inventorship and of right to grant of a patent required in support of this request? (*Answer 'Yes' if:*

- a) any applicant named in part 3 is not an inventor, or
- b) there is an inventor who is not named as an applicant, or
- c) any named applicant is a corporate body.

See note (d))

YES

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Description	10
Claim(s)	5
Abstract	1
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Statement of inventorship and right to grant of a patent (Patents Form 7/77)	-
Request for preliminary examination and search (Patents Form 9/77)	YES
Request for substantive examination (Patents Form 10/77)	-
Any other documents (please specify)	-

11. I/We request the grant of a patent on the basis of this application.

Signature
Forrester Ketley & Co.

Date
12 November, 2002

12. Name and daytime telephone number of person to contact in the United Kingdom
David J Lucking
0121 236 0484

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DUPLICATE

PATENTS ACT 1977

A10634GB-DJL

Title: Method of Handling a Load

Description of Invention

This invention relates to a method of handling a load with a mobile loading machine such as a wheeled loading machine.

Wheeled loading machines which have a loading arm which may be raised and lowered and extended and retracted to deliver or collect a load are known. However for the load to be accurately positioned for delivery, e.g. at height, or for a load to be collected from a height, it is a requirement that the machine is manoeuvred such that when the arm is raised a loading implement for handling the load, is laterally aligned with the desired position for unloading or loading.

It will be appreciated that for safety reasons, to maintain the stability of the loading machine when manoeuvred, the arm when carrying a load is in a lowered condition. Thus in the event that a load is to be delivered to a high position and the machine operator does not accurately laterally align the machine, when the arm is raised the load will not be deliverable to the desired load delivery position. Thus to comply with safety requirements, the operator must lower the loaded arm again before manoeuvring the machine in an effort to more accurately laterally to align the machine. This is time consuming and can lead to the operator manoeuvring the machine with the load lifted to a high position, which is contrary to safety requirements.

Proposals have been put forward to allow the loading implement to be shiftable sideways, so that in the event of a minor lateral misalignment when the load is raised, the load can be shifted sideways towards the load delivery position with the arm in a raised condition. However shifting a heavy load

sideways can lead to lateral instability of the machine, and in any event to provide for such lateral side shifting of the load, the arm/loading implement needs to be provided with additional actuators.

According to one aspect of the invention we provide a method of handling a load at a high desired load handling position using a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the method including the steps of manoeuvring the machine with the arm in the lower travelling position generally below the load handling position, and then one of:

a) directing a signal from the machine towards the load handling position in a plane in which a reference point of the loading implement is movable as the arm is raised about the generally horizontal axis, or

b) directing a signal from at or adjacent the load handling position in a plane in which a reference point of the loading implement would be moveable if the arm is raised about the generally horizontal axis with the machine in a correct lateral position,

to ascertain whether the machine is correctly laterally positioned so that if the arm is lifted the loading implement is positionable at the load handling position, manoeuvring the machine as necessary until the machine is correctly laterally positioned and then raising the loading arm to raise the loading implement towards the load delivery position.

Thus utilising the method of the invention, there is no need for an operator to raise the arm to see if the machine is correctly laterally aligned with the load handling position for the load to be delivered or collected.

Where the signal is directed from the machine towards the load handling implement the signal may be a simple light beam, a fan of light in the plane of

movement of the reference point of the loading arm so that it is unnecessary to adjust a beam up and down in the plane to direct the light at the load handling position. Thus, correct lateral positioning can be checked by the operator viewing where the directed light falls.

The light is preferably a high intensity light such as collimated laser light so that the light can be seen by the machine operator even on a bright day.

The reference point of the loading implement may be a laterally central position of the loading implement, which may lie generally along an elongate axis of the loading arm or the reference point may lie to one or other side of the axis as required.

The signal may be directed towards the load handling position from an signalling device carried on the loading arm or on the body of the machine as necessary to direct the light in the plane.

Where the signal is directed in a plane from at or adjacent the load handling position towards the machine, the signal may be light receivable by a receiver such as a sight of the machine, at least when the machine is correctly laterally positioned, or a non-visible signal such as a sonic or non-visible electromagnetic signal, receivable by an appropriate receiver on the machine.

The method may include not only raising the loading arm to deliver or collect a load from the load handling position, but where the arm includes a plurality of relatively telescopic sections, extending the arm to move the loading implement axially of the arm towards the load handling position for unloading or loading.

The loading implement may typically be a loading fork but other kinds of loading implements may be utilised in the performance of the invention.

According to a second aspect of the invention we provide a method of handling a load at a high desired load handling position using a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a

lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the method including the steps of directing a signal from at or adjacent the load handling position and manoeuvring the machine with the arm in the lower travelling position generally below the load handling position, until the signal is received by a receiver of the machine to indicate that the machine is in a correct lateral position so that if the arm is raised, the loading implement is positionable at the load handling position, and then raising the loading arm to raise the loading implement towards the load delivery position.

This aspect of the invention may require an illuminating or other signalling device to be located at or adjacent to the load handling position or a target to be positioned at or adjacent the load handling position, from which the signal may pass to the receiver. In each case depending upon the geometry of the machine, the receiver may be located adjacent the machine operator so that the machine operator may use the receiver directly visually. Alternatively, the receiver may be provided by a camera which provides a signal to a screen viewer which may be viewed by the machine operator.

In each case the operator may obtain knowledge of where the loading implement may be positioned upon raising, prior to the loading arm being raised.

According to a third aspect of the invention we provide a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the machine being manoeuvrable with the arm in the lower travelling position to below a high load handling position, the machine further including an device for directing a signal towards the load handling position in a plane in which a

reference point of the loading implement is movable as the arm is raised about the generally horizontal axis.

~~The signalling device may produce a fan or beam of light.~~

According to a fourth aspect of the invention we provide a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the machine including a receiver, the machine being manoeuvrable with the arm in the lower travelling position to generally below the load handling position, as necessary until a signal from at or adjacent the load handling position is received by the receiver to indicate that the machine is in a correct lateral position.

The signal may be light and the receiver may be a viewer which is located adjacent the machine operator so that the machine operator may use the viewer directly visually. Alternatively, the receiver may be provided by a camera which provides a signal to a screen viewer which may be viewed by the machine operator.

Embodiments of the invention will now be described with reference to the accompanying drawings in which:-

FIGURE 1 is a side view of a mobile loading machine for use in a first embodiment of the invention, adjacent a load handling position;

FIGURE 2 is a rear view of the machine of figure 1;

FIGURE 3 is a side view of a mobile loading machine for use in a second embodiment of the invention, adjacent a load handling position;

FIGURE 4 is a rear view of the machine of figure 3.

Referring to figure 1, a loading machine 10 is shown which includes a body 11 carried on a ground engaging structure which in this example includes front 12 and rear 13 ground engaging wheels by means of which the machine

10 may be driven over the ground by a machine operator in an operator's cab 14 at one side of the body 11.

At least one of the front 12 and rear 13 wheels are steerable, and the machine 10 may be powered by an engine E or motor which may be side mounted as shown on an opposite side of the body 11 to the cab 14, and driven over the ground by a mechanical and/or hydrostatic transmission, as desired..

The machine has a loading arm 15 which in this case includes a pair of telescoped sections 16, 17, but in another embodiment may have more than two sections 16, 17. A first of the arm sections, section 16, is connected to the body 11 of the machine 10 so that the arm 15 is mounted for up and down movement about a generally horizontal axis A by one or more actuators 18, between the engine E and the cab 14, and a second arm section 17 carries a loading implement 20 which in this case is a loading fork, but other loading implements may be utilised.

The fork 20 is mounted for pivotal movement relative to the arm 15 about a second generally horizontal axis B by one or more actuators 21.

Thus far the machine 10 is generally conventional.

However, in accordance with a first aspect of the invention, the machine 10 is provided with an illuminating device 25 which in this case is mounted on a top of the loading arm 15, and when required, produces a fan F of intense preferably collimated, preferably laser light.

A reference point is provided, in this example, at a central position C of the loading fork 20. As the loading arm 15 is raised and lowered by the actuators 18 about the axis A, the reference point C moves in a generally vertical plane, at least where the machine 10 is in a level attitude. The illuminating device 25 is located such that the fan F lies in the plane P.

In the case of a machine operator wishing to discharge a load L carried by the fork 20 at a high load handling position such as a platform 30 of a scaffolding tower 31, as seen in the drawings, the operator drives the machine

with the loading arm 15 in a lowered travelling position shown in full lines in figure 1, and manoeuvres the machine 10 to bring the machine 10 to a position adjacent but below the high load handling position 30.

Before raising the loading arm 15 to raise the loading fork 20 and hence the load L towards the platform 30, the lateral alignment of the machine 10 with respect to the platform 30 can be checked by operating the illuminating device 25. If the platform 30 is struck by the fan F of light, the operator will know that by raising the arm 15, the reference point of the loading fork 20 will move in the plane of the fan F, and thus the load L may be discharged at the platform 30. Of course some extension of the arm 15 may be required too, in order to position the load L on the platform.

If desired, instead of a fan F of light, the illuminating device 25 may produce a beam, but in this case it may be necessary to provide for up and down adjustment of the beam in the plane P so that the beam may be directed to the platform 30 or other load handling position, whatever the height of the position.

If it is desired to collect a load from the platform 30 for example, the empty loading fork 20 may be raised to the platform after checking the lateral alignment of the machine 10 by directing light to the platform 30.

If desired, instead of mounting the illuminating device 25 on the loading arm 15, the device 25 may be mounted on a mount M of the arm 15, or on the side of the arm 15 or even on the body 11 of the machine e.g. on the cab 14, wherever it is necessary to mount the device according to the machine 10 geometry, so that the device 25 can direct light in the plane P or another reference plane from which the operator can determine the lateral alignment of the machine 10 relative to the load handling position e.g. platform 30.

In order for the directed light to be seen by the operator, the light produced by the illuminating device 25 must be sufficiently intense and/or coloured or otherwise arranged to be easily visible by the operator.

Preferably the light is in the normal visual spectrum readily visible by the operator without assistance, but the light may be in a spectrum requiring special glasses of the like to see it, for example ultraviolet or infrared light.

Referring to figures 3 and 4 an alternative embodiment is shown. In this example a loading machine substantially similar to that shown in figures 1 and 2 is shown with similar parts labelled by the same reference numerals.

In this embodiment, no illuminating device is provided on the machine 10. Rather an illuminating device 25' is provided on the platform 30 where the load L is to be handled. The illuminating device 25' directs a fan F' or a beam, in a plane P' with which the machine 10 must be laterally aligned, for the loading fork 20 to be raised to the platform 30 for handling the load L.

The light is received by a viewer V which is usable by the operator in the cab 14 directly visually. The viewer V includes a sight S (see inset to drawing). In use, the operator manoeuvres the machine 10 below the platform 30 until the light directed from the illuminating device 25' on the platform 30 coincides with the sight S, at which position, the operator knows the machine 10 is laterally aligned with the platform 30.

The viewer V in this example is located on the top of the cab 14 of the machine 10, to receive the directed light, and the illuminating device 25' is positioned to one side of the platform so that the sight S may be aligned with the plane P' in which the light is directed. In another embodiment, the viewer may be mounted on the loading arm 15 or elsewhere of the machine 10 to be alignable with the plane P' when the machine 10 is correctly aligned with the platform 30.

The viewer V includes internally a reflector, so that the operator can view the sight S from a screen 19 within the cab 14. In another example though, the sight S may be provided by a camera in the position of the viewer V, which camera receives the light from the illuminating device 25' and provides a signal

to a viewing screen 19 in the operator's cab 14, so that the operator can view when the machine 10 is correctly laterally aligned with the platform 30.

It will be appreciated that provided there is a reference point on the platform 30, it may not be essential to provide an illuminating device 25 thereon, as the sight S may be able to receive ambient light reflected from any suitable reference point which it is known is positioned so that when the arm 15 is raised, the loading fork 20 will be raised to the platform 30 for load handling. In that case, the viewer V or camera may need to be focusable to enable the sight to be focused on the reference point.

Where there is no clear reference point on the platform 30, if desired a target may be provided at the platform 30 which may be viewed via the viewer V or camera and the machine 10 manoeuvred until the machine is laterally aligned with respect to the target.

In the examples described, light is used as a signal between the machine 10 and reference point of platform 30. In another example, a non-visible signal may be used.

For example a sonic or non-visible electromagnetic signal may be used by providing a suitable transmitting device on the machine 10 and/or at or adjacent the load handling position, and a receiver at/or adjacent to the load handling position and/or machine 10 respectively.

For example the machine 10 may have one or more directional microphones to receive a sonic signal from a transponder provided at/or adjacent to the load handling position, or the machine 10 may have a radar type transmitting device and receiver, and electronic signal processing means to detect the direction of a target at or adjacent the load handling position.

Although in the examples described, the loading machine 10 has been a wheeled loading machine 10, the invention may be used with any kind of mobile loading machine.

Although the embodiments of the invention as described include reference to the machine operator, the invention lends itself for use where the ~~loading machine is a robotically operated machine, with a remote human~~ operator and/or a computer controlled operator.

The features disclosed in the foregoing description, or the following claims, or the accompanying drawings, expressed in their specific forms or in terms of a means for performing the disclosed function, or a method or process for attaining the disclosed result, as appropriate, may, separately, or in any combination of such features, be utilised for realising the invention in diverse forms thereof.

CLAIMS

1. A method of handling a load at a high desired load handling position using a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the method including the steps of manoeuvring the machine with the arm in the lower travelling position generally below the load handling position, and then one of:

a) directing a signal from the machine towards the load handling position in a plane in which a reference point of the loading implement is movable as the arm is raised about the generally horizontal axis, or

b) directing a signal from at or adjacent the load handling position in a plane in which a reference point of the loading implement would be moveable if the arm is raised about the generally horizontal axis with the machine in a correct lateral position,

to ascertain whether the machine is correctly laterally positioned so that if the arm is lifted the loading implement is positionable at the load handling position, manoeuvring the machine as necessary until the machine is correctly laterally positioned and then raising the loading arm to raise the loading implement towards the load delivery position.

2. A method according to claim 1 wherein the signal is directed from the machine towards the load handling position, and the signal is light which is directed as a fan of light in the plane of movement of the reference point.

3. A method according to claim 1 or claim 2 wherein the light is high intensity light such as collimated laser light.

4. A method according to any one of the preceding claims wherein the reference point of the loading implement is a laterally central position of the loading implement, which lies generally along an elongate axis of the loading arm.
 5. A method according to any one of claims 2 to 4 wherein the light is directed towards the load handling position from an illuminating device carried on the loading arm or on the body of the machine as necessary to direct the light in the plane.
 6. A method according to claim 1 wherein the signal is directed from at or adjacent the load handling position towards the machine, and the signal is receivable by a receiver of the machine at least when the machine is correctly laterally positioned.
 7. A method according to any one of the preceding claims wherein where the arm includes a plurality of relatively telescopic sections, the method includes extending the arm to move the loading implement axially of the arm towards the load handling position.
 8. A method according to any one of the preceding claims wherein the loading implement is a loading fork.
 9. A method of handling a load at a high desired load handling position using a mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for
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carrying the load, the method including the steps of directing a signal from at or adjacent the load handling position and manoeuvring the machine with the arm in the lower travelling position generally below the load handling position, until the signal is received by a receiver of the machine to indicate that the machine is in a correct lateral position so that if the arm is raised, the loading implement is positionable at the load handling position, and then raising the loading arm to raise the loading implement towards the load delivery position.

10. A method according to claim 9 wherein one of a signalling device and a target is located at or adjacent the load handling position, from which the signal passes to the receiver.

11. A method according to claim 9 or claim 10 wherein the receiver is located adjacent the machine operator so that the machine operator may use the receiver directly visually.

12. A method according to claim 9 or claim 10 wherein the receiver is provided by a camera which provides a signal to a screen viewer which may be viewed by the machine operator.

13. A method of handling a load substantially as hereinbefore described with reference to figures 1 and 2 or figures 3 and 4 of the accompanying drawings.

14. A mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the machine being manoeuvrable with the arm in the lower travelling position to below a high load handling position, the machine further

including an device for directing a signal towards the load handling position in a plane in which a reference point of the loading implement is movable as the arm is raised about the generally horizontal axis.

15. A machine according to claim 14 wherein the signalling device produces a fan or beam of light.

16. A mobile loading machine of the kind having a loading arm connected at one end to a body of the machine for movement at least about a generally horizontal axis between a lower travelling position, and a higher load handling position, and the arm having at its outermost end a loading implement for carrying the load, the machine including a receiver, the machine being manoeuvrable with the arm in the lower travelling position to generally below the load handling position, as necessary until a signal from at or adjacent the load handling position is received by the receiver to indicate that the machine is in a correct lateral position.

17. A machine according to claim 16 wherein the signal is light and the receiver is a viewer which is located adjacent the machine operator so that the machine operator may use the viewer directly visually.

18. A machine according to claim 16 wherein the receiver is provided by a camera which provides a signal to a screen viewer which may be viewed by the machine operator.

19. A mobile loading machine substantially as hereinbefore described with reference to and/or as shown in figures 1 and 2 or figures 3 and 4 of the accompanying drawings.

20. Any novel feature or novel combination of features described herein
and/or as shown in the accompanying drawings.

ABSTRACT

Title: Method of Handling a Load

A method of handling a load (L) at a high desired load handling position (30) using a mobile loading machine (10) of the kind having a loading arm (15) connected at one end to a body (11) of the machine (10) for movement at least about a generally horizontal axis (A) between a lower travelling position, and a higher load handling position, and the arm (15) having at its outermost end a loading implement (20) for carrying the load, the method including the steps of manoeuvring the machine with the arm in the lower travelling position generally below the load handling position, and then one of:

a) directing a signal from the machine (10) towards the load handling position in a plane (P) in which a reference point of the loading implement (20) is movable as the arm (15) is raised about the generally horizontal axis (A), or

b) directing a signal from at or adjacent the load handling position in a plane (P) in which a reference point of the loading implement (20) would be moveable if the arm (15) is raised about the generally horizontal axis (A) with the machine (10) in a correct lateral position,

to ascertain whether the machine (10) is correctly laterally positioned so that if the arm (15) is lifted the loading implement (20) is positionable at the load handling position, manoeuvring the machine (10) as necessary until the machine is correctly laterally positioned and then raising the loading arm (15) to raise the loading implement (20) towards the load delivery position.

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